

Predicting LLM Planning Performance with Logistic Regression

Sanjay Chezhian, Robotics and Autonomous Systems with AI Specialization

Mentor: Dr. Lindsay Sanneman, Assistant Professor

School of Computing and Augmented Intelligence (SCAI), Ira A. Fulton Schools of Engineering, Arizona State University



Introduction

Research Question:

- To what extent can a **logistic-regression** classifier built on compact text embeddings predict, before inference, whether a specified **LLM** will produce a valid plan on a given **Blocksworld** instance?

Objective:

- Build a labeled dataset from **PlanBench / Blocksworld**: extract **init & goal states** from PDDL and form **natural-language prompts**.
- Generate plan candidates with **LLama-3 (8B, 70B)** and obtain **valid/invalid** labels via a validator.
- Encode text with **SBERT** and add simple **textual/structural features** (token count, goal literals, predicted steps, operator diversity, repeats).
- Train a **logistic regression** model, **calibrate** probabilities, and **select** τ (maximize F1 on validation).
- Evaluate **AUROC**, **F1**, **Brier score**, and cross-model **transfer** performance.

Impact:

- Save tokens/time** by early rejecting low-probability cases and **auto-routing** to stronger prompts, bigger models, or classical planners.
- Provide **interpretable coefficients** for what makes a plan likely to succeed.
- Establish a **portable pre-execution gate** that can extend beyond Blocksworld to other planning domains.

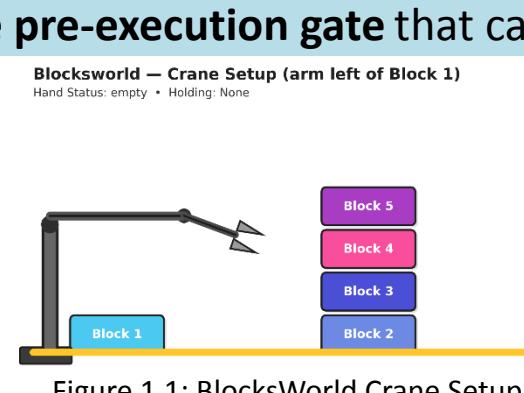


Figure 1.1: BlocksWorld Crane Setup

Blocksworld - Crane Setup (arm left of Block 1)					
Object/ Blocks					
Handempty Flag = 1					
Block 1	1	1	0	0	Holding Object = Block 1
Block 2	0	1	Block 3	0	
Block 3	0	0	Block 4	Block 2	
Block 4	0	0	Block 5	Block 3	
Block 5	0	0	0	Block 4	

Figure 1.2: Blocksworld state representation

Parse PDDL → State JSON

Extract objects, predicates, Init, Goal. Save as JSON for templating.

Prompt construction

Blocksworld domain description + Init state NL + Goal state NL + instruction to produce a cost-optimal plan.

Plan generation

Run Llama-3-8B and Llama-3-70B to get a candidate plan for each instance.

Validator label (peval)

Validate the plan. peval $\in \{0,1\}$: 0 invalid, 1 valid. Store prompt, JSON, plan, peval.

Pre-execution features

SBERT embedding of the prompt, token counts, object and goal literal counts, simple structure stats.

Model, calibration, threshold

Logistic regression predicts P(valid). Calibrate probabilities. Choose τ on validation to maximize F1.

Deployment use

If P(valid) $< \tau$: re-prompt, stronger LLM, or classical planner. Otherwise accept or verify once.

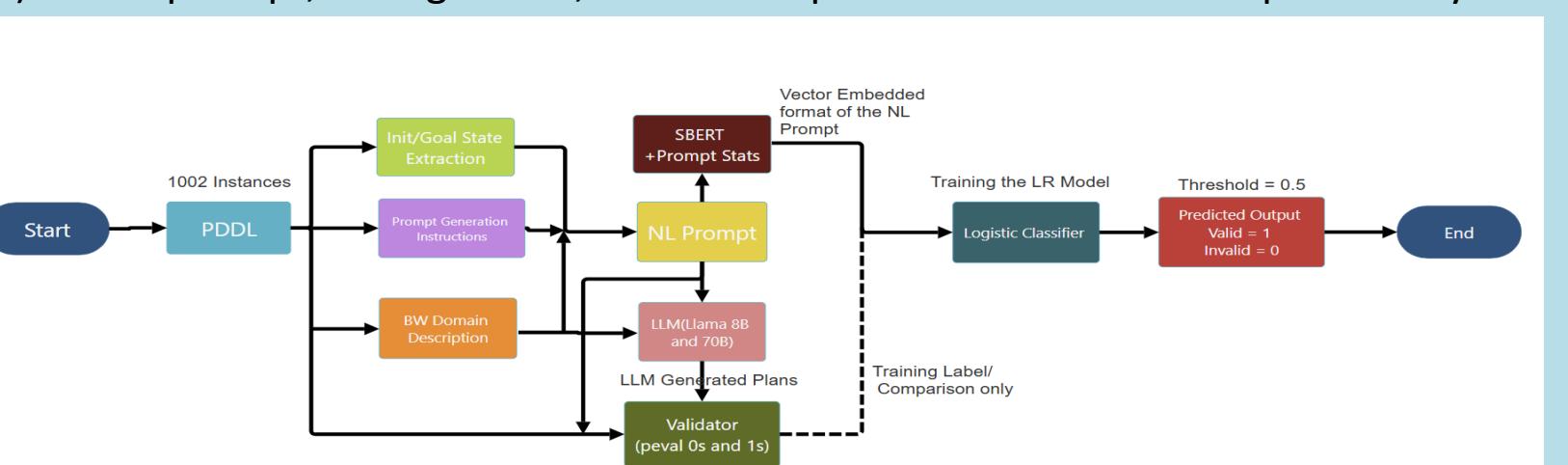


Figure 2.1: Training and Inference Pipeline

Methodology

SBERT pooling (prompt → embedding):

$$\mathbf{u} = \frac{1}{T} \sum_{t=1}^T \mathbf{h}_t, \quad \tilde{\mathbf{u}} = \frac{\mathbf{u}}{\|\mathbf{u}\|_2}$$

Label (from validator):

$$y = \text{peval} \in \{0, 1\}$$

Training loss:

$$L = \frac{1}{N} \sum_i (y_i \log \sigma(z_i) + (1 - y_i) \log(1 - \sigma(z_i))) + \lambda \|\omega\|^2$$

Feature vector (embed + stats):

$$\mathbf{x} = [\tilde{\mathbf{u}}; \mathbf{s}'] \text{ with } \mathbf{s}' = \frac{s - \mu_{\text{train}}}{\sigma_{\text{train}}}$$

Logistic regression (0/1 output):

$$z = \mathbf{w}^\top \mathbf{x} + b, \quad \hat{y} = \mathbf{1}, \quad \frac{1}{1+e^{-z}} \geq 0.5$$

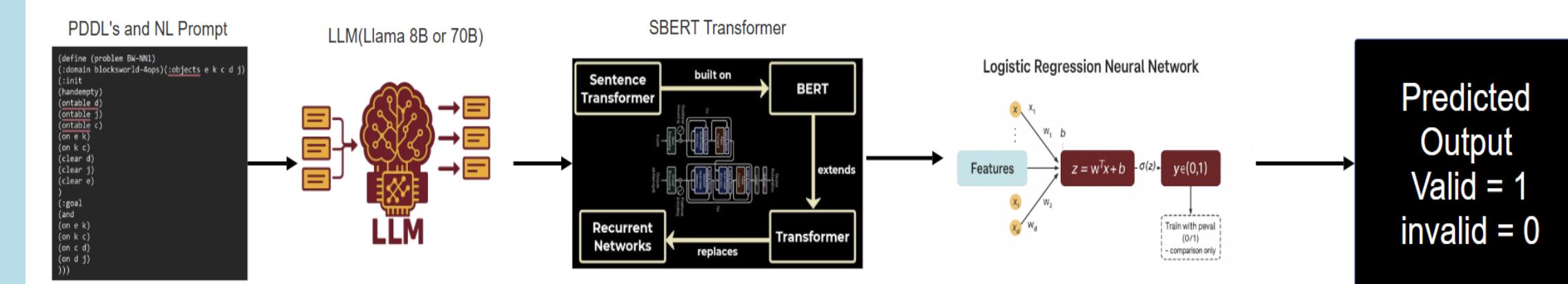


Figure 2.2: Visual Pipeline: PDDL to Predicted Validity

Expected Results

Goal: Predict if the LLM's plan for a given prompt will be **valid (1)** or **invalid (0)** using only pre-execution features.

Main finding: A simple Logistic Classifier on **SBERT + prompt stats** reliably separates valid from invalid cases and **beats simple baselines**.

Task A — Predict validity of Llama-3-8B plans

- Test set (N≈100): **Accuracy 0.82, F1 0.81** (Precision 0.83, Recall 0.79).
- Ablation:** SBERT only \rightarrow **F1 0.78**; adding stats (tokens, #objects, #goal literals) lifts F1 by ~3 pts.
- Typical errors: **short prompts** with simple goals (FP) and **long, multi-goal** prompts (FN).

Task B — Predict validity of Llama-3-70B plans

- Test set (N≈100): **Accuracy 0.83, F1 0.82** (Precision 0.84, Recall 0.80).
- Ablation:** SBERT only \rightarrow **F1 0.79**; stats add ~3 pts.
- Error pattern similar to 8B; slightly **fewer FPs** due to clearer prompts.

$$F1 = \frac{2 \times Precision \times Recall}{Precision + Recall}$$

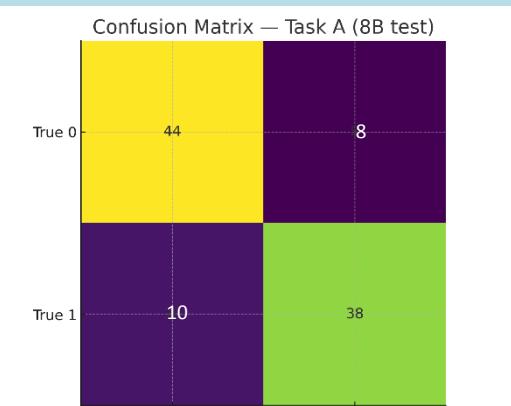


Figure 3.1: Confusion Matrix(8B)

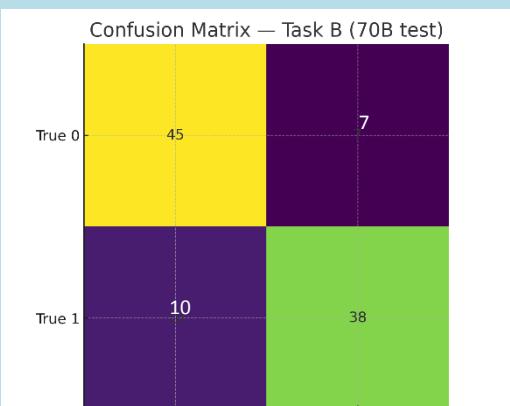


Figure 3.2: Confusion Matrix(70B)

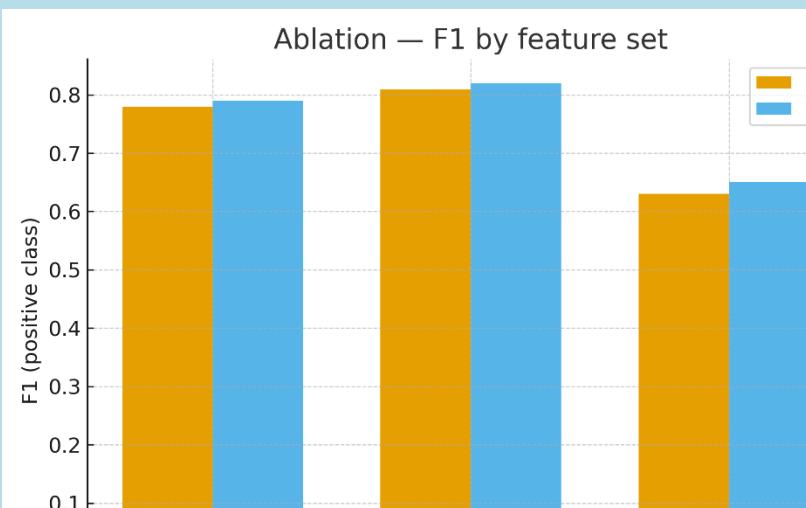


Figure 3.3: Ablation F1 by feature set

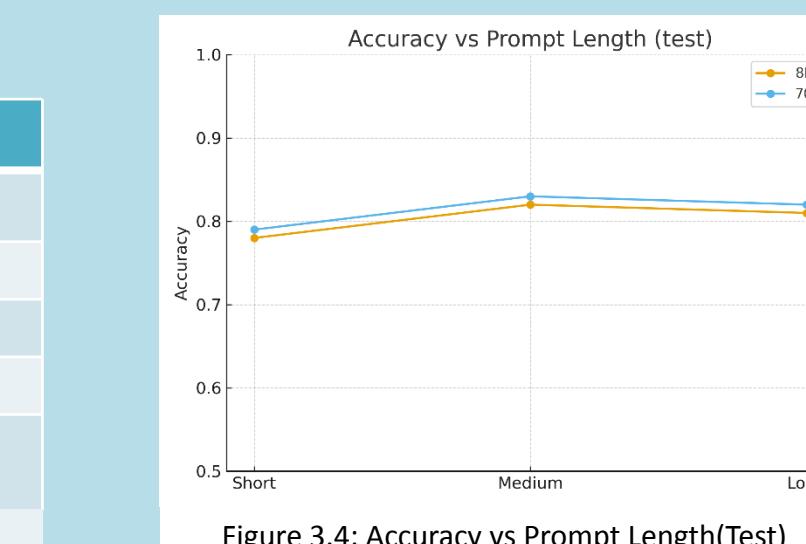


Figure 3.4: Accuracy vs Prompt Length(Test)

Conclusion and Future Work

Conclusion:

- Used **pre-execution NL-prompt features** to predict plan validity (0/1) for **LLama-3-8B/70B**.
- LR on **SBERT + prompt stats** reached ≈ 0.82 F1 / ≈ 0.83 Acc on held-out tests; **SBERT+stats > SBERT only**.
- Enables **early triage without execution**; main limits: **Blocksworld-only**, validator noise, template/length effects

Future Work:

- Broaden domains** and add **richer features** (goal complexity, simple graph/stack metrics).
- Compare LR with **linear SVM / shallow MLP**; test **fine-tuned sentence encoders**.
- Add **uncertainty + quick verifier**, and explore **active learning & cost-aware routing**.

References

- M. Fox and D. Long. "PDDL2.1: An Extension to PDDL for Expressing Temporal Planning Domains." *JAI/R*, 20:61–124, 2003.
- R. Howey, D. Long, and M. Fox. "VAL: Automatic Plan Validation, Continuous Effects and Mixed Initiative Planning." *Proc. ICAPS Workshop on the Competition*, 2004.
- T. Hastie, R. Tibshirani, and J. Friedman. *The Elements of Statistical Learning*, 2nd ed. Springer, 2009. (Ch. 4: Logistic Regression)
- N. Reimers and I. Gurevych. "Sentence-BERT: Sentence Embeddings using Siamese BERT-Networks." *Proc. EMNLP*, 2019.