

Generative AI-Aided Navigation for the Visually Impaired and Blind Kelly Raines, Computer Science (Software Engineering) Mentor: Ransalu Senanayake, Assistant Professor School of Computing and Augmented Intelligence (SCAI)

Introduction

Motivation: Reduce one of the most significant barriers to freedom for the visually impaired and blind [1] who account for around 2.2 billion people worldwide [2]

Current solutions are **insufficient**:



Limited information below the knee, up to only a few feet radius around the user [3]

Navigation apps cannot capture a real-time, dynamic environment

Research Goal: Improve <u>safety</u>, independence, and <u>confidence</u> through a reliable <u>personal navigation assistant</u> that will answer queries at any moment





TO

Figure 2: Decision Matrix Determines Best VLM

Results

GPT-40

Spatial Reasoning Categories	Baseline GPT-40	GPT-4o with Context
Right	11/20	13/20
Left	6/15	11/15
Above	5/9	6/9
Below	20/27	17/27
In Front	12/14	12/14
Behind	3/8	6/8

Logic Reasoning:

EX: Crossing Road

8/8 Tests Passed ✓

Error Handling:

EX: Obscured Object,

Misheard Query, etc.

15/25 points achieved

YOLO

Known Object Accuracy: 73.33%

Unknown Object Accuracy: 80.77%

MiDaS

Indoor Error **Outdoor Error Total Error**

Human Range & Standard Deviation: 24.15 ft & +/-22.27 ft



Proposed Solution

Receive Audible

Response

You are

nearby 3

buildings

Figure 1: User Flow of Navigation Assistant

Criteria	Weight	VLM Scores: 1 (worst) - 5 (best)		
		VQA/Vilt	Moondream	GPT-4o
al Reasoning	3	2	4	3
ail Accuracy	3	1	2	5
Control	2	1	1	4
Speed	2	5	3	4
Cost	1	5	5	3
TAL SCORE	-	26	31	43

	Human	MiDaS		
	2.31 ft	1.86 ft		
	13.84 ft	7.04 ft		
	9.64 ft	5.15 ft		

Latency



Query & Image Sent

to GPT-40

GPT: 6.114 seconds YOLO: 2.046 seconds

MiDaS: 3.527 seconds



second

Group Type



- Hardware: Ray-Ban Meta Smart Glasses
- Software: GPT-4o, YOLO, MiDaS



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References

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