

# **Non-Metallic Bio Polymer Composite Design and Selection for Replacement of Rigid Non-Degradable Orthopedic BioWare**



# **INTRODUCTION**

This project aims to validate the properties of polymer-ceramic composites experimentally, utilizing designated ASTM standards. Building upon previous research that utilized GRANTA software to estimate mechanical properties, this work extends the analysis by incorporating finite element models. The rule of mixtures (ROM) was used for the previous research, which is a simple and approximate way of predicting the tensile strength of fiber-reinforced composites [2]. However, ROM is not effective to predict the accurate value of the

composite [2]. Hence, modified ROM is used to get the more accurate prediction The ultimate objective is to utilize computational data to create a bio-composite design for bone fixation devices. By leveraging the mechanical property estimates obtained from computational analysis, non-metallic composite bone fixation devices will be developed for orthopedic applications.

### **METHODS**

- Halpin Tsai equation [Eqn 1] is a micromechanical model used to estimate the effective mechanical properties of composite materials based on the properties of their individual constituents [3].
- This method is very popular in both micro and nano mechanics because of its simplicity. In this method, the longitudinal and transverse moduli (EL and ET) of composites were calculated [3].

$$E_{L} = E_{m} \frac{1 + 2\frac{l}{t} \eta_{L} V_{f}}{1 - \eta_{L} V_{f}}, E_{T} = E_{m} \frac{1 + 2\eta_{T} V_{f}}{1 - \eta_{T} V_{f}}$$

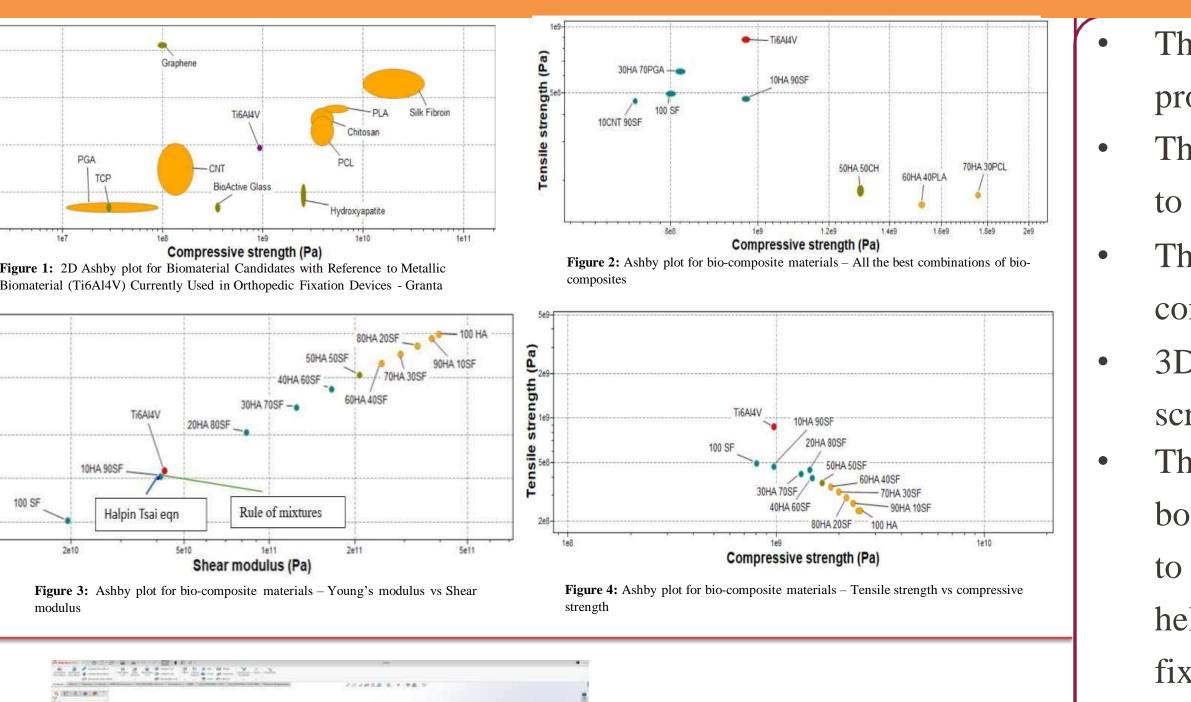
$$\eta_{L} = \frac{\frac{E_{r}}{E_{m}} - 1}{\frac{E_{r}}{E_{m}} + 2\frac{l}{t}}, \eta_{T} = \frac{\frac{E_{r}}{E_{m}} - 1}{\frac{E_{r}}{E_{m}} + 2}$$
[Eqn. 1]

 $E_m$  and  $E_r$  are the elastic moduli of the matrix and reinforcement,  $E_L$  and  $E_T$  are the longitudinal and transverse moduli respectively, 1 is length of reinforcement, r and t are the radius and thickness of the platelet reinforcement respectively, V is the volume fraction of the material.

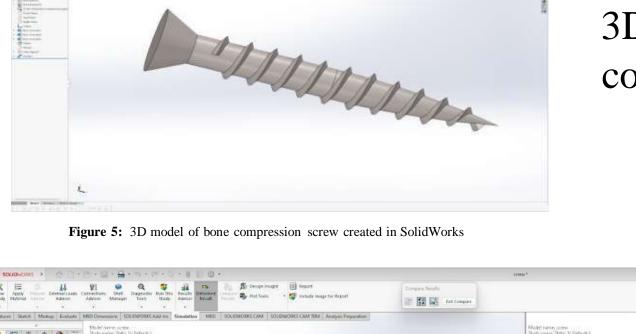


Sri Manaswini Palaparthi, Biomedical Engineering, SBHSE Mentors: Vincent Pizziconi, Ph.D; Dr. Erwin Kruger, M.D., Mayo Clinic

### RESULTS



3D simulations for bone compression screw with load at the tip



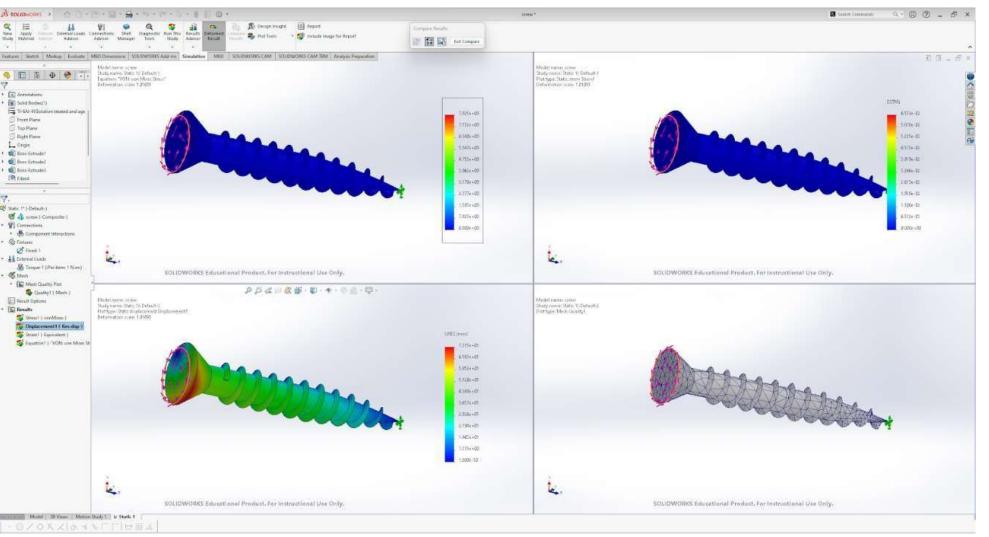


Figure 6: Simulation for bone compression screw in SolidWorks

# **SUMMARYAND CONCLUSIONS**

This study demonstrates the utility of computational models to provide early estimates of composite material systems.

This study will help to minimize the number of experimental trials to verify optimal composite material contributions.

This will also serve as a basis for developing more detailed computational finite element analysis (FEA) models (Ansys).

3D model made with the help of SolidWorks of bone compression screw (Fig 5) which is the basis for the experimental model.

This study shows the simulation to the 3D model of bio-composite bone compression screw by incorporating Elastic modulus values to the composite where Halpin Tsai equation is the firm basis that helps to develop further with the non-metallic composite bone fixation device.

### **REFERENCES**

Hassanzadeh-Aghdam, M.K., Jamali, J. A new form of a Halpin–Tsai micromechanical model for characterizing the mechanical properties of carbon nanotube-reinforced polymer nanocomposites. Bull Mater Sci 42, 117 (2019)

Luo Z, Li X, Shang J, Zhu H, Fang D. Modified rule of mixtures and Halpin–Tsai model for prediction of tensile strength of micron-sized reinforced composites and Young's modulus of multiscale reinforced composites for direct extrusion fabrication. Advances in Mechanical Engineering. 2018;10(7)

3. Mahmood M. Shokrieh, Hadi Moshrefzadeh-Sani, On the constant parameters of Halpin-Tsai equation, Polymer, Volume 106, 2016

4. Chart created using CES EduPack 2019, ANSYS Granta © 2020 Granta Design 5. Rohit Mali, Uday Pise,

6. Modeling elastic properties of biocomposites using various analytical models and ansys material designer, Materials Today: Proceedings, Volume 72, Part 3, 2023

# ACKNOWLEDGEMENTS

I would like to thank Dr. Vincent Pizziconi for assisting me in this project and also thank him for giving me the opportunity to work in this ASU-Mayo collaborative project where I developed many design skills. I also thank Prof. Michael Sobrado for providing mechanical test training that will help guide mechanical characterization of physical prototypes.

> Engineering Arizona State University

